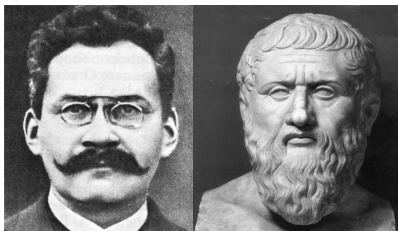


Shape Dynamics

International Loop Quantum Gravity Seminar

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Literature

Original:

- H. Gomes, S. Gryb, T.K.: "Einstein gravity as a 3D conformally invariant theory," CQG 28 (2011) 045005. [arXiv:1010.248];
- H. Gomes, T.K.: "The Link between General Relativity and Shape Dynamics," [arXiv:1101.5974];
- H. Gomes, S. Gryb, T.K., F. Mercati: "The gravity/CFT correspondence," [arXiv:1105.0938];
- T. Budd, T.K.: "Shape Dynamics in 2+1 Dimensions," [arXiv:1107.1287];
- H. Gomes, T.K.: "Coupling Shape Dynamics to Matter Gives Spacetime," [arXiv:1110.3837];
- T.K.: "Loop Quantization of Shape Dynamics", (sorry, not yet out)

Introduction:

- H. Gomes: "The Dynamics of Shape," [arXiv:1108.4837];
- T.K.: "Shape Dynamics," [arXiv:1108.5224]

Background:

- J. Barbour: "Shape Dynamics: An Introduction," [arXiv:1105.0183]

Work in progress:

- T.K.: "Symmetry Doubling";
- H. Gomes, T.K.: "Constructing Shape Dynamics";
- H. Gomes, S. Gryb, T.K., N.N.: "Shape Dynamics Perturbation Theory."

Outline

- **Introduction**
- **Symmetry Trading:** Linking Theories, Canonical best Matching
- **Construction of Shape Dynamics:** Best matching ADM, Linking Theory, Shape Dynamics
- **Challenges and Answers:** Spacetime Picture, Nonlocality, Non-CMC solutions
- **Tentative Loop Quantization:** SD in Ashtekar variables, kinematic loop quantization, tentative “dynamics”, “interpretation”
- **Summary and Outlook:** *“There are many open questions.”*

What is Shape Dynamics?

Short Answer:

Shape Dynamics is a formulation of GR where refoliation symmetry is traded for local spatial conformal symmetry.

It is just a reformulation of GR. Why bother?

- **Ontology:** Different Symmetry \Rightarrow different theory space for effective field theory (Hořva)
- **Access to new aspects:** e.g. classical large CMC-volume/CFT correspondence
- **Quantization Opportunities:** e.g. Dirac quantization of metric gravity on 2+1 sphere and torus

Canonical Framework

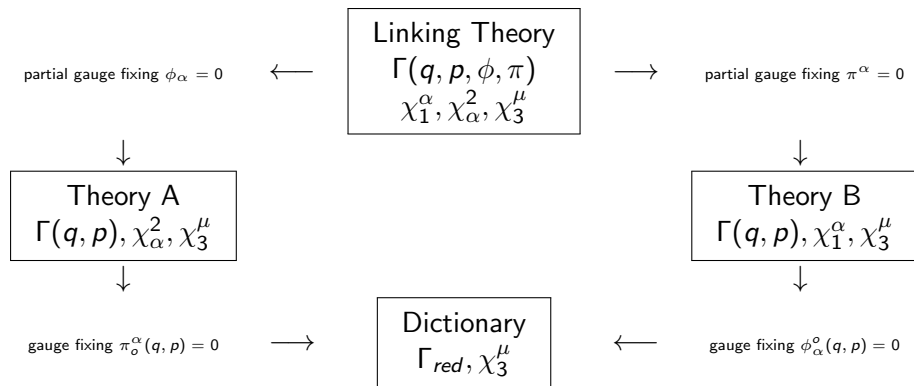
Canonical System $(\Gamma, \{.,.\}, H, \{\chi_i^{fir.}\}_{i \in \mathcal{I}}, \{\chi_j^{sec.}\}_{j \in \mathcal{J}})$

- Obtained from singular Legendre transform of **consistent** Lagrangian
- form of constraints is **not** determined by Legendre transform
- assume regular, irreducible first class constraints $\{\chi_i^{fir.}\}_{i \in \mathcal{I}}$
- **Dirac conjecture:** First class secondary constraints generate gauge transformations. (counter example: $L = e^y \dot{x}^2$)
- **Gauge fixing:** regular, irreducible set $\{\sigma_i\}_{i \in \mathcal{I}} \cup \{\chi_i^{fir.}\}_{i \in \mathcal{I}}$, such that $\{\chi_i^{fir.}, \sigma_j\}$ is invertible
- **Reduced phase space:** $\Gamma_{red} = \Gamma|_{\{\chi_j^{sec.}=0\}_{j \in \mathcal{J}}}$ with **Dirac** bracket $\{.,.\}_D$

From now on:

- assume energy conservation constraint $\chi_o^{fir.} = H - E$
- second class constraints are solved, i.e. $\{\chi_j^{sec.}\}_{j \in \mathcal{J}} = \emptyset$

Linking Gauge Theories and Symmetry Trading



where $\chi_1^\alpha = 0$ is equiv. $\pi^\alpha = \pi_\alpha^\alpha(q, p)$ and $\chi_\alpha^2 = 0$ is equiv. $\phi_\alpha = \phi_\alpha^\alpha(q, p)$

Equivalence of Gauge Theories on $(\Gamma, \{., .\})$

\exists gauge fixing with identical trajectories (same IVP and EOM)

Canonical Best Matching (an implementation of J. Barbour's Machian ideas)

Goal: Implement symmetry $q_i \rightarrow Q_i(q, \phi)$

first class system $(\Gamma, \{.,.\}, H, \{\chi^\mu\}_{\mu \in M})$, group param. ϕ_α

Construction

- phase space extension $\Gamma \rightarrow \Gamma \times \Gamma(\phi, \pi)$
- equivalence with orig. Γ through first class constraints $\pi^\alpha \approx 0$
- canonical transformation (generator) $F = Q_i(q, \phi)P^i + \phi_\alpha \Pi^\alpha$ takes $\pi^\alpha \rightarrow \pi^\alpha - \pi_\alpha^\alpha(q, p)$
- Impose best matching condition $\pi^\alpha = 0$:
 - (1) π^α commutes \Rightarrow orig. system had gauge invariance
 - (2) π^α gauge fixes some $\chi^\mu \Rightarrow$ equivalence of gauge theories
 - (3) π^α generates secondary constraints \Rightarrow complete Dirac procedure

in general one obtains mixture of these three cases

Canonical General Relativity (you know that)

ADM formulation

- Global hyperbolicity; for now also Σ is compact without boundary
- Poisson bracket $\{F(g), \pi(f)\} = F(f)$
- spatial diffeomorphism constraints $H(v) = \int_{\Sigma} d^3x \pi^{ab} (\mathcal{L}_v g)_{ab}$
- local refoliation constraints

$$S(N) = \int_{\Sigma} d^3x N \left(\frac{1}{\sqrt{|g|}} \pi^{ab} G_{abcd} \pi^{cd} - \sqrt{|g|} (R - 2\Lambda) \right)$$

Generic IVP and Regularity:

are strictly proven in $\pi = g_{ab} \pi^{ab} = \text{const. gauge}$. (Only few extensions.)

Linking GR and Shape Dynamics

ADM best matched w.r.t. VPCT

- extend phase space by canonical pair $\phi(x), \pi_\phi(x)$
 - generating functional $F = \int d^3x \left(g_{ab} e^{4\hat{\phi}} \Pi^{ab} + \phi \Pi_\phi \right)$, where $\hat{\phi} = \phi - \frac{1}{6} \ln \langle e^{6\phi} \rangle_g$
- canonical transformation $T : \pi_\phi \mapsto \pi_\phi - 4 \left(\pi - \langle \pi \rangle_g \sqrt{|g|} \right)$
- impose $\pi_\phi = 0$ and work out reduced phase space
 - volume preserving condition leaves one Hamilton constraint behind
- \Rightarrow **matching trajectories** (SD in ADM-gauge = GR in CMC-gauge)

Shape Dynamics on $(\Gamma_{ADM}, \{\cdot, \cdot\}_{ADM})$

diffeomorphism: $H(\xi) = \int d^3x \pi^{ab} \mathcal{L}_\xi g_{ab}$

loc. conformal trf.: $D(\rho) = \int d^3x \rho (\pi - \langle \pi \rangle_g \sqrt{|g|})$

Hamiltonian: $H_{SD} = \int d^3x TS_{ADM}(x)|_{\phi=\phi_o(g,\pi)}$

where ϕ_o satisfies inhomogeneous Lichnerowicz-York equation and $\langle e^{6\phi} \rangle_g = 1$ (\exists existence proof).

Pure Shape Dynamics (trajectories vs. IVP)

Dirac algebra is traded for **Shape Dynamics algebra**

$[S(N_1), S(N_2)] = H(N_1 \nabla N_2 - N_2 \nabla N_1)$	$[D(\rho_1), D(\rho_2)] = 0$
$[H(\xi), S(N)] = S(\mathcal{L}_\xi N)$	$[D(\rho), H_{SD}] = 0$
$[H(\xi_1), H(\xi_2)] = H([\xi_1, \xi_2])$	$[H(\xi), D(\rho)] = D(\mathcal{L}_\xi \rho)$
	$[H(\xi), H_{SD}] = 0$
	$[H(\xi_1), H(\xi_2)] = H[\xi_1, \xi_2]$

- Nonlin. constraints traded for linear constraints and nonloc. Hamiltonian
- Implies different Theory Space for Quantum Gravity.

for IVP (fixed time slice): lift volume preservation

- trade $S(N)$ for $D(\rho) = \int_\Sigma d^3x \rho \left(\pi \pm \sqrt{8\Lambda} \sqrt{|g|} \right)$.
- locality, but **frozen** dynamics (fixed time slice)

Objection 1: “You have no Spacetime Picture.”

Answer: No.

Use a minimally coupled test multiplet (as clocks/rods) to recover spacetime operationally.

Relationalist: You should do the same in GR.

Real Problem:

Universality of recovered spacetime (all fields see same spacetime).

Possible way out:

Symmetry Doubling: SD and GR BRST-invariances at the same time.
(this is work currently in progress, see “Outlook”)

Coupling Matter to Shape Dynamics

Construction

- Best matching of ADM+matter system w.r.t. VPCT
 - Shape Dynamics through phase space reduction
- ⇒ **Equivalence** with GR+matter system by construction

Conformal weight for matter?

- Constraint-decoupling (conf., diffeo., gauge) as guiding principle
- ⇒ **Solution** for bosonic Standard Model: conformal weight 0 for all matter

$$F = \int_{\Sigma} d^3x \left(e^{4\hat{\phi}} g_{ab} \Pi^{ab} + \phi \Pi_{\phi} + A_a^i \mathcal{E}_i^a + \varphi^{\alpha} \Pi_{\alpha} + \dots \right)$$

Shape Dynamics-matter system:

- ADM $S(N) \Rightarrow$ SD-Ham. H_{SD} and $Q(\rho) = \int_{\Sigma} \rho \left(\pi - \langle \pi \rangle \sqrt{|g|} \right)$
- diffeomorphism- and gauge constraints are unaltered
- restrictions on $\langle \pi \rangle$ **only** from cosmological constant and Higgs potential

Objection 2: “It’s just the York procedure.”

Key differences with York procedure

- York procedure concerns only IVP (decoupling of constraints), SD concerns dynamics (propagation of constraints)
 \Rightarrow Hamiltonian needs lapse fixing equation (York) vs. Lichnerowicz-York-equation (SD).
- Volume preserving condition (**not** used by York) is essential for equivalence of trajectories and gives correct scaling.
- Best matching is **canonical** transformation (SD) vs. manual TT-decomposition (York)

Summary:

The existence of SD is based in the same existence theorems as York, but the construction and consequences are fundamentally different.

Objection 3: “Your Hamiltonian is Unmanageable.”

Yes, pertaining to classical trajectories. But:

- classically, one can work in ADM gauge then $H_{SD} = H_{ADM}(N \equiv 1)$
- once one is interested in **generic** IVP solution one needs to fix gauge also in ADM

then ADM suffers from the same complications

H_{SD} can be constructed explicitly in:

- $2 + 1$ -dimensions (on sphere and torus)
- Strong gravity limit (precisely: whenever spatial derivatives negligible)
- perturbation theory around ADM solutions (in particular cosmological perturbation theory, WIP)

Gravity in 2+1 Dimensions

One of the 2+1 Tricks

$g = e^{2\lambda} f^* g(\tau)$ and TT-decomp. of π reduces GR to Teichmüller-sp dyn.

SD on 2+1 Torus

- lin. constr. $H(v) = \int_T d^2x \pi^{ab} (\mathcal{L}g)_{ab}$, $D(\rho) = \int_T d^2x \rho (\pi - \langle \pi \rangle \sqrt{|g|})$
- SD-Hamilton constraint $H_{SD} = \frac{\tau^2}{2V} (p_1^2 + p_2^2) - \frac{V}{2} (\langle \pi \rangle^2 - 4\Lambda)$

Dirac Quant. = Reduced phase space Quant.

- Set $\hat{\pi}^{ab} = i\hbar \frac{\delta}{\delta g_{ab}}$ \Rightarrow linear constraints imply $\psi[g[\lambda, f; \tau_1, \tau_2]] = \psi(\tau_1, \tau_2)$
 $\Rightarrow H_{SD} = -\tau_2^2 (\partial_{\tau_1}^2 + \partial_{\tau_2}^2) + V^2 (\partial_V^2 + 4\Lambda)$ (equal to reduced phase space Hamiltonian)

Large CMC-Volume Expansion

- genus $\geq 2 \Rightarrow V/V_o$ -expans.: $H_{SD} = -\frac{V}{2} (\langle \pi \rangle^2 - 4\Lambda) - R + \mathcal{O}(\frac{1}{V})$
- works in higher dimensions (large CMC-volume/CFT-correspondence)

Objection 4: “Non-CMC solutions to Einstein’s equations.”

Answer:

This is a restriction compared to GR (like global hyperbolicity).

However:

Boundaries are in principle treatable (see future projects).
If dynamical boundaries are also treatable then one could possibly circumvent some of these restrictions.

Shape Dynamics in Ashtekar-Barbero variables

Road map

triad var. $(e_a^i, \pi_i^a) \Rightarrow$ ext. curv. var. $(K_a^i, E_i^a) \Rightarrow$ Ashtekar var. (A_a^i, E_i^a)

Triad vars.: (e_a^i, π_i^a) , rotation const. $G(\lambda) = \int_{\Sigma} d^3x \lambda^i \epsilon_{ij}^k e_a^k \pi_k^a$

- best matching generator $F = \int_{\Sigma} d^3x \left(e_a^i e^{2\hat{\phi}} \Pi_i^a + \phi \Pi_{\phi} \right)$
- linear constr.: $H(v)$, $C(\rho)$ and $G(\lambda)$
- Hamiltonian: $H_{SD} = TS(N \equiv 1)|_{\phi=\hat{\phi}_0}$

$\Rightarrow (K_a^i, E_i^a)$ and can. trf. $F = \int d^3x (K_a^i \beta \tilde{E}_i^a + \tilde{E}_i^a \Gamma_a^i(\tilde{E}))$

Ashtekar vars.: (A_a^i, E_i^a) , Gauss constraint $G(\lambda)$

- linear constraints: $H(v)$ and $G(\lambda)$
- VPCT-generator: $C(\rho) = \int_{\Sigma} d^3x \rho \left((A_a^i - \Gamma_a^i) \tilde{E}_i^a - \langle (A_a^i - \Gamma_a^i) \tilde{E}_i^a \rangle \sqrt{|\tilde{E}|} \right)$
- Hamiltonian: $H_{SD} = TS(N \equiv 1)|_{\phi=\hat{\phi}_0}$ (retain Gauss-constr.)

Kinematic Loop Quantization

Do everything as in kinematic LQG:

- dense orthogonal set $T(A) = \prod_e \rho_{n_e m_e}^{j_e}(h_e(A))$
 - holonomy-matrix elements act by multiplication $\rho_{nm}^j(h(A))$
 - fluxes act as derivations $E(S, \lambda)$
 - solve Gauss- and diffeomorphism constraint
- \Rightarrow orthogonal set: gauge-inv. spin-knot functions

classical VPCT-invariants

- VPCTs of holonomies are unmanageable
 - VPCTs of fluxes are straightforward: $E_a^i(x) \mapsto e^{4\hat{\phi}(x)} E_a^i(x)$
- \Rightarrow total volume V and all angles (=gauge-inv. ratios) are **invariant**
- \Rightarrow all nonvanishing areas are **pure gauge**

Disclaimer

Warning

The following is a **naive** application of LQG methods to the IVP of SD only.

In particular be **critical** of:

- 1 No quantization of equivalent dynamics
- 2 Heuristic treatment of conf. trfs.

Tentative Quantization

Heuristic implementation of VPCTs

- choose recoupling basis \Rightarrow max. comm. set of angles
- determine SNF uniquely by (area-, angle-) eigenvalues and keep V_{tot}
 \Rightarrow areas are pure gauge \Rightarrow choose unique representative
 \Rightarrow knot, max. set of angles and V_{tot} label basis
- How quantize H_{SD} ???

For total Dirac procedure (fix time slice)

- trade **also** H_{SD} for $\langle \pi \rangle - \alpha V$ (can. trf. to $\langle \pi \rangle$)
 \Rightarrow basis labeled by knot, max. set of angles

Problem:

Can one get rid of recoupling choice?

A Questionable Interpretation

Objection:

Where is equivalence with CMC dynamics?

Large CMC-volume correspondence

- assume $\Lambda > 0$ and suitable initial data \Rightarrow asymptotic expansion
 - use V/V_o -expansion $\Rightarrow H_{SD} \rightarrow 12\Lambda - \langle \pi \rangle^2$
- \Rightarrow classical equivalent $\langle \pi \rangle \approx \pm \sqrt{12\Lambda}$

Questionable Interpretation

“The states in the mutual constraint kernel describe asymptotic shapes of the universe in the large volume limit.”

Summary

Features of Shape Dynamics

- 1 Shape Dynamics arises from trading refoliation invariance for local conformal invariance
- 2 Linking theories and canonical best matching provide general mechanism for symmetry trading
- 3 Existence theorems of for IVP ensure Shape Dynamics exists
- 4 SD on $2+1$ -torus in metric variables can be quantized without phase space reduction
- 5 large CMC-volume/CFT-correspondence
- 6 Works with standard matter content
- 7 Spacetime picture can be recovered operationally
- 8 tentative LQG-quantization

Outlook

Current Project: **Symmetry Doubling**

Observation: special $H_{BRST} = \sigma^\alpha \chi_\alpha + \dots$ is BRST invariant under **both** $\Omega_{orig} = \eta^\alpha \chi_\alpha + \dots$ and $\Omega_{dual} = \bar{\eta}_\alpha \sigma^\alpha + \dots$
 \Rightarrow small theory space

here: complete symmetry trading is admissible \Rightarrow locality

There are many open questions (examples):

- Symplectic geometry of symmetry trading/symmetry doubling
- Treatment of boundaries (e.g. isolated horizons)
- More advanced: dynamical boundaries (possibly non CMC?)
- Higher orders in perturbation theory
- SD-gauge transformations of solutions to GR
- Symmetry trading/symmetry doubling in other theories

Thank you!